

# Panel Data Econometrics<sup>1</sup>

(Yonsei University)

Min Seong Kim  
Ryerson University

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# 1 Introduction to Panel Data Model

## Basic Model

$$y_{it} = X_{it}\beta + \varepsilon_{it}, \quad i = 1, \dots, n, \quad t = 1, \dots, T$$

$X_{it}$  includes

- variables that vary across individuals and time periods. Denote them as  $X_{it}$ .
- variables that are time invariant. ie. vary only across individuals. Denote them as  $X_i$ .
- variables that vary only over time, not across individuals. Denote them as  $X_t$

## Type of panel data

- Large  $n$ , small  $T$  (micro-panel data)
  - Rely on the large  $n$  asymptotics in which  $n \rightarrow \infty$  with fixed  $T$ .
- Large  $T$ , small  $n$ 
  - Rely on the large  $T$  asymptotics in which  $T \rightarrow \infty$  with fixed  $n$ .
- Large  $n$ , large  $T$ 
  - Joint asymptotics:  $n, T \rightarrow \infty$  at the same time. Sometimes control the relative rate of expansion (eg.  $\sqrt{n}/T \rightarrow 0$ )
  - Sequential asymptotics:  $n \rightarrow \infty$  first, then  $T \rightarrow \infty$ . Or  $T \rightarrow \infty$  first, then  $n \rightarrow \infty$ .
- Small  $n$ , small  $T$ 
  - Not many things to do. Collect more data.

## Benefits of using panel data

- Efficiency

– For  $y_{it} = X_{it}\beta + \varepsilon_{it}$ ,

$$s.e.(\hat{\beta}) = \frac{\sigma}{\sqrt{\sum_{i=1}^n \sum_{t=1}^T (X_{it} - \mu)^2}}$$

- Dynamics

– 25% of women are unemployed.

\* Scenario 1: This 25% women are determined.

\* Scenario 2: This 25% women are randomly selected.

With panel we can tell between these scenario.

- Identification (Example: Agricultural production function)

$$y_{it} = \beta_1 K_{it} + \beta_2 L_{it} + \gamma Z_i + u_{it}$$

$y_{it}$  : farm output,  $K_{it}$  : Capital,  $L_{it}$  : Labor,  $Z_i$  : Soil quality,  $u_{it}$  : random shock (rainfall, ..)

- This is the production function from a farmer’s point of view.
- Econometricians cannot observe  $Z_i$  which is correlated with  $K_{it}, L_{it}$ . Let

$$X_{it} = K_{it}L_{it}, \beta = \beta_1\beta_2.$$

and

$$y_{it} = X'_{it}\beta + \varepsilon_{it}, \text{ with } \varepsilon_{it} = \gamma Z_i + u_{it}.$$

Then,

$$\hat{\beta} = \beta + \underbrace{\left( \sum_{i=1}^n \sum_{t=1}^T X_{it}X'_{it} \right)^{-1} \sum_{i=1}^n \sum_{t=1}^T X_{it}Z_i\gamma}_{\rightarrow 0} + \left( \sum_{i=1}^n \sum_{t=1}^T X_{it}X'_{it} \right)^{-1} \sum_{i=1}^n \sum_{t=1}^T X_{it}u_{it}$$

$\implies$  Omitted variable bias.

- But in panel data, this bias can be removed.

$$\Delta y_{it} = \beta_1 \Delta K_{it} + \beta_2 \Delta L_{it} + \Delta u_{it}.$$

## 2 Static Panel Data Model

### Model

$$y_{it} = X_{it}\beta + \varepsilon_{it}, \quad i = 1, \dots, n, \quad t = 1, \dots, T.$$

In static models,  $X_{it}$  does not include lagged dependent variables.

### Fixed Effects vs. Random Effects

$$y_{it} = X'_{it}\beta + \varepsilon_{it}.$$

Let  $\varepsilon_{it} = \alpha_i + u_{it}$ . In our example,  $\alpha_i = \gamma Z_i$ .

- $\alpha_i$  : individual effect or individual heterogeneity
- $u_{it}$  : idiosyncratic error.

When  $E(\alpha_i|X_i) = 0$ , we say the model is a random effect model. Otherwise, it is a fixed effects model.

## Random Effects Approach

### Assumptions

1.  $E(\alpha_i|X_i) = 0$ ,  $E(u_{it}|X_i, \alpha_i) = 0$
2.  $\alpha_i \sim iid$ ,  $u_{it} \sim iid$ .  $u_{it}$  is independent of  $\alpha_j$ .
3.  $\text{Rank}(E[X_i'\Omega^{-1}X_i]) = k$  with  $E(\varepsilon_i\varepsilon_i') = \Omega$ .
4.  $E(\alpha_i^2|X_i) = \sigma_\alpha^2$ ,  $E(u_i u_i'|X_i) = \sigma_u^2 I_T$

Under these assumptions,

$$\begin{aligned} E\varepsilon_{it}\varepsilon_{js} &= E(\alpha_i + u_{it})(\alpha_j + u_{js}) \\ &= \begin{cases} \sigma_\alpha^2 + \sigma_u^2 & \text{if } i = j \text{ and } t = s, \\ \sigma_\alpha^2 & \text{if } i = j \text{ and } t \neq s, \\ 0 & \text{if } i \neq j \text{ and } t \neq s. \end{cases} \end{aligned}$$

Thus,

$$\Omega = \text{var}(\varepsilon_i) = \sigma_u^2 I_T + \sigma_\alpha^2 J_T$$

where  $J_T$  is the  $T \times T$  matrix with unity in every element.

Let's use matrix notation

$$y = X\beta + \varepsilon$$

where

$$\varepsilon = \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} \text{ and } \varepsilon_i = \begin{bmatrix} \varepsilon_{i1} \\ \vdots \\ \varepsilon_{iT} \end{bmatrix}.$$

Then, we have

$$\begin{aligned} \text{var}(\varepsilon|X) &= I_n \otimes \Omega \\ &= V \end{aligned}$$

### GLS estimator

$$\begin{aligned} y &= X\beta + \varepsilon, \quad \varepsilon|X \sim (0, V) \\ V^{-1/2}y &= V^{-1/2}X\beta + V^{-1/2}\varepsilon. \end{aligned}$$

Therefore, the GLS estimator for random effects model is

$$\begin{aligned} \hat{\beta}_{REGLS} &= (X'V^{-1}X)^{-1} X'V^{-1}y \\ &= (X'(I_n \otimes \Omega^{-1})X)^{-1} X'(I_n \otimes \Omega^{-1})y \\ &= \left( \sum_{i=1}^n X_i'\Omega^{-1}X_i \right)^{-1} \sum_{i=1}^n X_i'\Omega^{-1}y_i. \end{aligned}$$

### Asymptotic Inference

- Under Assumptions 1,2 and 3,  $\hat{\beta}_{REGLS}$  is consistent.
- Under Asymptotics 1,2,3 and 4,  $\hat{\beta}_{REGLS}$  is the BLUE.

### Feasible GLS

We need to estimate  $\Omega$ , or  $\sigma_u^2$  and  $\sigma_\alpha^2$ .

$$\hat{\beta}_{OLS} = \left( \sum_{i=1}^n \sum_{t=1}^T X_{it} X'_{it} \right)^{-1} \sum_{i=1}^n \sum_{t=1}^T X_{it} y_{it}$$

is consistent under the assumptions above. So, we can estimate  $\sigma_\varepsilon^2$  ( $\varepsilon_{it} = \alpha_i + u_{it}$ ) with

$$\hat{\sigma}_\varepsilon^2 = \frac{1}{nT - k} \sum_{i=1}^n \sum_{t=1}^T \left( y_{it} - X'_{it} \hat{\beta}_{OLS} \right)^2$$

As  $\sigma_\alpha^2 = E(\varepsilon_{it} \varepsilon_{is})$  for  $t \neq s$ ,

$$\hat{\sigma}_\alpha^2 = \frac{1}{nT(T-1)/2 - k} \sum_{i=1}^n \sum_{t=1}^{T-1} \sum_{s=t+1}^T \left( y_{it} - X'_{it} \hat{\beta}_{OLS} \right) \left( y_{is} - X'_{is} \hat{\beta}_{OLS} \right)$$

Plugging  $\hat{\sigma}_\varepsilon^2$  and  $\hat{\sigma}_\alpha^2$  in  $\Omega$ , we obtain  $\hat{\Omega}$  and

$$\hat{\beta}_{REFGLS} = \left( \sum_{i=1}^n X'_i \hat{\Omega}^{-1} X_i \right)^{-1} \sum_{i=1}^n X'_i \hat{\Omega}^{-1} y_i.$$

### Understanding the GLS estimator

Recall  $V = \text{var}(\varepsilon) = I_n \otimes \Omega$ . As

$$\Omega = \sigma_\alpha^2 J_T + \sigma_u^2 I_T,$$

$$V = (T\sigma_\alpha^2 + \sigma_u^2) P + \sigma_u^2 Q,$$

where  $P = I_n \otimes J_T/T$  and  $Q = I_{nT} - P$ . Let  $\sigma_1^2 = T\sigma_\alpha^2 + \sigma_u^2$ . Then,

$$V^{-1} = \sigma_1^{-2} P + \sigma_u^{-2} Q$$

and

$$V^{-1/2} = \sigma_u^{-1} \left( I_{nT} - \left( 1 - \frac{\sigma_u}{\sigma_1} \right) P \right).$$

If we premultiply the regression model

$$y = X\beta + \varepsilon$$

by

$$\sigma_u V^{-1/2} = (\sigma_u/\sigma_1) P + Q,$$

then we have

$$y_{it} - \theta \bar{y}_i = (X_{it} - \theta \bar{X}_i)' \beta + (\varepsilon_{it} - \theta \bar{\varepsilon}_i)$$

where

$$\theta = 1 - \frac{\sigma_u}{\sigma_1}.$$

The error term  $(\varepsilon_{it} - \theta \bar{\varepsilon}_i)$  are uncorrelated and have the same variance across all  $i$  and  $t$ . Thus, OLS based on the above regression model (quasi-demeaned equation) is the BLUE.

## Fixed Effects Approach

$$y_{it} = X_{it}' \beta + \alpha_i + u_{it}$$

Now, we assume that  $X_{it}$  and  $\alpha_i$  are correlated. Then, the random effects estimator is biased.

$$\hat{\beta}_{REGLS} = \beta + \left( \sum_{i=1}^n X_i' \Omega^{-1} X_i \right)^{-1} \sum_{i=1}^n X_i' \Omega^{-1} (\alpha_i + u_{it})$$

eg.  $y_{it}$  = farm output,  $X_{it}$  = capital, labor,  $\alpha_i$  = soil quality;  $y_{it}$  = birth weight,  $X_{it}$  = smoking habit,  $\alpha_i$  = other health related habits

### Assumptions

1.  $E(u_{it} | X_i, \alpha_i) = 0$
2.  $\text{Rank}[E(X'QX)] = k$ .
3.  $E[u_i u_i | X_i, \alpha_i] = \sigma_u^2 I_T$

### Estimation strategy

The idea is to transform the equation to eliminate the unobserved effect  $\alpha_i$ . Here we consider fixed effects transformation, which is also called within transformation.

1. Average equation  $y_{it} = X_{it}' \beta + \alpha_i + u_{it}$  over  $t$  to get  $\bar{y}_i = \bar{X}_i' \beta + \alpha_i + \bar{u}_i$  with  $\bar{y}_i = T^{-1} \sum_{t=1}^T y_{it}$ .
2. Take difference.

$$y_{it} - \bar{y}_i = (X_{it} - \bar{X}_i)' \beta + u_{it} - \bar{u}_i \Leftrightarrow Qy = QX\beta + Qu$$

Note that under Assumption 1,

$$E(u_{it} - \bar{u}_i)(X_{it} - \bar{X}_i) = 0$$

for all  $t$  and  $s$ . Thus, OLS estimator from the transformed model is consistent and unbiased.

$$\begin{aligned} \hat{\beta}_{FE} &= \left( \sum_{i=1}^n \sum_{t=1}^T (X_{it} - \bar{X}_i)(X_{it} - \bar{X}_i)' \right)^{-1} \sum_{i=1}^n \sum_{t=1}^T (X_{it} - \bar{X}_i)(y_{it} - \bar{y}_i) \\ &= (X'QX)^{-1} X'Qy \end{aligned}$$

## Asymptotic inference

$$\sqrt{n}(\hat{\beta}_{FE} - \beta) \rightarrow^d N\left(0, \sigma_u^2 (EX'QX)^{-1}\right)$$

As

$$\begin{aligned} E\hat{u}'\hat{u} &= E\left[u'Qu - u'QX(X'QX)^{-1}X'Q'u\right] \\ &= (N(T-1) - k)\sigma_u^2. \end{aligned}$$

This implies an unbiased estimator for  $\sigma_u^2$  is

$$\hat{\sigma}_u^2 = \frac{SSR}{N(T-1) - k}.$$

## Robust variance matrix estimator

Assumption 3 may be very strong. The fixed effects estimator is consistent and asymptotically normal under assumptions 1 and 2. In the presence of possible heteroskedasticity and autocorrelation,

$$\text{var}\left(\hat{\beta}_{FE}\right) = E\left[(X'QX)^{-1}X'Quu'Q'X(X'QX)^{-1}\right].$$

But,

$$\begin{aligned} X'Quu'Q'X &= \sum_{i=1}^n \sum_{j=1}^n (X_i - \bar{X}_i)' u_i u_j' (X_j - \bar{X}_j) \\ X'QX &= \sum_{i=1}^n (X_i - \bar{X}_i)' (X_j - \bar{X}_j) \end{aligned}$$

Under the cross-sectional independence assumption  $\left(E(u_i u_j' | X) = 0 \text{ for } i \neq j\right)$

$$\begin{aligned} \text{var}\left(\hat{\beta}_{FE}\right) &= E\left(\sum_{i=1}^n (X_i - \bar{X}_i)' (X_j - \bar{X}_j)\right)^{-1} \left(\sum_{i=1}^n (X_i - \bar{X}_i)' u_i u_i' (X_i - \bar{X}_i)\right) \\ &\quad \times \left(\sum_{i=1}^n (X_i - \bar{X}_i)' (X_j - \bar{X}_j)\right)^{-1}. \end{aligned}$$

Based on this, we can estimate the  $\text{var}\left(\hat{\beta}_{FE}\right)$  with

$$\left(\sum_{i=1}^n (X_i - \bar{X}_i)' (X_j - \bar{X}_j)\right)^{-1} \left(\sum_{i=1}^n (X_i - \bar{X}_i)' \hat{u}_i \hat{u}_i' (X_i - \bar{X}_i)\right) \left(\sum_{i=1}^n (X_i - \bar{X}_i)' (X_j - \bar{X}_j)\right)^{-1}.$$

## Random Effects Estimator vs. Fixed Effects Estimator

### Comparison between two estimators

Note that

$$\hat{\beta}_{REGLS} = (X'V^{-1}X)^{-1}XV^{-1}y$$

where

$$V^{-1} = \sigma_1^{-2}P + \sigma_u^{-2}Q \text{ and } \sigma_1^2 = T\sigma_\alpha^2 + \sigma_u^2.$$

- If  $\sigma_\alpha^2 = 0$ , then  $\sigma_1^2 = \sigma_u^2$  so  $\hat{\beta}_{REGLS} = \hat{\beta}_{POLLS}$ .
- If  $T \rightarrow \infty$ , then  $\hat{\beta}_{REGLS} \rightarrow \hat{\beta}_{FE}$ .
- If  $\sigma_\alpha^2 \rightarrow \infty$ , then  $\hat{\beta}_{REGLS} \rightarrow \hat{\beta}_{FE}$ . The larger  $\sigma_\alpha^2$ , the closer  $\hat{\beta}_{REGLS}$  is to  $\hat{\beta}_{FE}$ .
- $var(\hat{\beta}_{REGLS}) = (\sigma_1^{-2}X'PX + \sigma_u^{-2}X'QX)^{-1}$  and  $var(\hat{\beta}_{FE}) = (\sigma_u^{-2}X'QX)^{-1}$ . Hence,  $var(\hat{\beta}_{REGLS}) \leq var(\hat{\beta}_{FE})$ .

### Hausman-Wu test

$$y_{it} = X'_{it}\beta + \alpha_i + u_{it}$$

#### Empirical Question: Which estimator should we use?

- $cov(\alpha_i, X_{it}) = 0$  for all  $t$  vs.  $cov(\alpha_i, X_{it}) \neq 0$  for some  $t$

#### Assumptions

1.  $E(\alpha_i) = 0$ ,  $E(u_{it}|\alpha_i, X_i) = 0$ .
2.  $E(\alpha_i^2|X_i) = \sigma_\alpha^2$ ,  $E(u_i u'_i|X_i) = \sigma_u^2 I_T$
3.  $\alpha_i \sim iid$  over  $i$ ,  $u_{it} \sim iid$  over  $i$  and  $t$ .

$H_0: cov(\alpha_i, X_{it}) = 0$  for all  $t$ . vs.  $H_1: cov(\alpha_i, X_{it}) \neq 0$  for some  $t$

	$\hat{\beta}_{REGLS}$	$\hat{\beta}_{FE}$	$\hat{\beta}_{REGLS} - \hat{\beta}_{FE}$
$H_0$	efficient	inefficient	small $\rightarrow 0$
	consistent	consistent	
$H_1$	inconsistent	consistent	Not small $\nrightarrow 0$

We consider a test statistic

$$q = (\hat{\beta}_{FE} - \hat{\beta}_{REGLS})' \hat{W}^{-1} (\hat{\beta}_{FE} - \hat{\beta}_{REGLS}),$$

where

$$W = var(\hat{\beta}_{FE} - \hat{\beta}_{REGLS})$$

If  $H_0$  is true,

$$\sqrt{n}(\hat{\beta}_{FE} - \hat{\beta}_{REGLS}) \rightarrow^d N(0, Q_0) \text{ with } Q_0 = \lim_{n \rightarrow \infty} var(\sqrt{n}(\hat{\beta}_{FE} - \hat{\beta}_{REGLS}))$$



and thus

$$q \rightarrow^d \chi_k^2 \text{ with } k = \dim(\beta).$$

We can show

$$\text{cov}(\hat{\beta}_{FE}, \hat{\beta}_{REGLS}) = \text{var}(\hat{\beta}_{REGLS}).$$

Therefore, under  $H_0$

$$\text{var}(\hat{\beta}_{FE} - \hat{\beta}_{REGLS}) = \text{var}(\hat{\beta}_{FE}) - \text{var}(\hat{\beta}_{REGLS}).$$

Based on this, we construct the test statistic

$$q = (\hat{\beta}_{FE} - \hat{\beta}_{REGLS})' \left( \hat{\sigma}_u^2 (X'QX)^{-1} - (X'\hat{V}X)^{-1} \right)^{-1} (\hat{\beta}_{FE} - \hat{\beta}_{REGLS})$$

### 3 Dynamic Panel Data Model

#### Models with sequentially exogenous variables

Consider

$$y_{it} = X_{it}'\beta + \alpha_i + u_{it}$$

#### Assumptions

1.  $E\alpha_i = Eu_{it} = 0$
2.  $E(u_{it}|X_{it}, \dots, X_{i1}, \alpha_i) = 0$  : sequential exogeneity ( $\text{cov}(X_{is}, u_{it}) \neq 0$  for  $s > t$ ).  
 $\Leftrightarrow E(u_{it}|X_i, \alpha_i) = 0$  : strict exogeneity

#### Fixed effect estimator

$$y_{it} - \bar{y}_i = (X_{it} - \bar{X}_i)\beta + (u_{it} - \bar{u}_i)$$

$$\hat{\beta}_{FE} \xrightarrow{p} \beta + \left( \frac{1}{T} \sum_{t=1}^T E(X_{it} - \bar{X}_i)(X_{it} - \bar{X}_i)' \right)^{-1} \underbrace{\frac{1}{T} \sum_{t=1}^T E(X_{it} - \bar{X}_i)u_{it}}_{(*)}$$

$$(*) = \frac{1}{T} \sum_{t=1}^T E(X_{it}u_{it} - \bar{X}_i u_{it}) = -E\bar{X}_i \bar{u}_i$$

For simplicity, assume  $E\bar{X}_i = 0$  and  $X_{it}$  is a scalar. Then,

$$E\bar{X}_i \bar{u}_i = O(1/T).$$

### First difference estimator

$$\hat{\beta}_{FD} \xrightarrow{p} \beta + \left( \frac{1}{T-1} \sum_{t=2}^T E \Delta X_{it} \Delta X'_{it} \right)^{-1} \underbrace{\frac{1}{T-1} \sum_{t=1}^T E \Delta X_{it} \Delta u_{it}}_{(**)}$$

$$(**) = -EX_{it}u_{it-1} = O(1)$$

### Anderson-Hsiao (AH) estimator

Consider the FD model.

$$\Delta y_{it} = \Delta X'_{it} \beta + \Delta u_{it}.$$

Under the sequential exogeneity assumption,

$$EX_{is}u_{it} = 0 \text{ for } s = 1, \dots, t.$$

and

$$E\Delta X_{is}\Delta u_{it} = 0 \text{ for } s = 1, \dots, t-1.$$

Thus, we can use  $\Delta X_{it-1}$  as an instrument for  $\Delta X_{it}$ . We can also use  $X_{it-1}$  and  $X_{it-2}$  as instruments.

### Arellano-Bond estimator (Panel GMM estimator)

AH IV estimator is consistent, but it is not efficient because it does not take into account all the available moment restrictions.

$$\Delta y_{it} = \Delta X'_{it} \beta + \Delta u_{it}.$$

Let  $X'_{it} = \underbrace{(X'_{i1} \ X'_{i2} \ \dots \ X'_{iT})}_{1 \times kt}$ . Define

$$Z_i = \underbrace{\begin{bmatrix} X'_{i1} & 0 & \dots & 0 \\ 0 & X'_{i2} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & X'_{iT-1} \end{bmatrix}}_{KT(T-1)/2}$$

Then,

$$EZ_i \Delta u_i = 0 \text{ where } \Delta u_i = [\Delta u_2 \ \Delta u_3 \ \dots \ \Delta u_T]'$$

In addition to the moment condition, we need the following rank condition to identify  $\beta$ .

**Assumption**  $\text{Rank}(EZ'_i\Delta X_i) = k$ .

$$\hat{\beta}_{GMM} = \arg \min \left( \sum_{i=1}^n Z'_i(\Delta y_i - \Delta X_i\beta) \right)' W \left( \sum_{i=1}^n Z'_i(\Delta y_i - \Delta X_i\beta) \right)$$

The GMM estimator of  $\beta$  is

$$\begin{aligned} \hat{\beta}_{GMM} &= \left[ \left( \frac{1}{n} \sum_{i=1}^n \Delta X'_i Z_i \right) W \left( \frac{1}{n} \sum_{i=1}^n Z'_i \Delta X_i \right) \right]^{-1} \\ &\quad \times \left( \frac{1}{n} \sum_{i=1}^n \Delta X'_i Z_i \right) W \left( \frac{1}{n} \sum_{i=1}^n Z'_i \Delta y_i \right) \\ &= (\Delta X' Z W Z' \Delta X)^{-1} \Delta X' Z W Z' \Delta y. \end{aligned}$$

### Asymptotics

Under the orthogonality and rank conditions, we can show that  $\hat{\beta}_{GMM}$  is consistent. We can also show that  $\hat{\beta}_{GMM}$  is asymptotically normal

$$\sqrt{n}(\hat{\beta}_{GMM} - \beta) \rightarrow^d N(0, V_\beta)$$

where

$$V_\beta = (C'WC)^{-1}C'W\Lambda WC(C'WC)^{-1},$$

using the fact that

$$\frac{1}{\sqrt{n}} \sum_{i=1}^n Z'_i \Delta u_i \rightarrow^d N(0, \Lambda).$$

### Selecting the weighting matrix

The optimal  $W$  is

$$W_{opt} = \Lambda^{-1} = \text{var} \left( \frac{1}{\sqrt{n}} \sum_{i=1}^n Z'_i \Delta u_i \right) = \frac{1}{n} \sum_{i=1}^n E(Z'_i \Delta u_i \Delta u'_i Z_i).$$

Without homoskedasticity,

$$\text{var} \left( \frac{1}{\sqrt{n}} \sum_{i=1}^n Z'_i \Delta u_i \right) = E[Z'_i \Delta u_i \Delta u'_i Z_i]$$

### A feasible GMM procedure

- 1 Let  $\hat{\beta}$  be an initial consistent estimator of  $\beta$ , for example,  $\hat{\beta} = \hat{\beta}_{2SLS}$ .
- 2 Define  $\Delta \tilde{u}_i = \Delta y_i - \Delta X_i \hat{\beta}_{2SLS}$
- 3 Construct a consistent estimator of  $\hat{\Lambda} = n^{-1} \sum_{i=1}^n Z'_i \tilde{u}_i \tilde{u}'_i Z_i$  and choose  $\hat{W} = \hat{\Lambda}^{-1}$
- 4 Use  $\hat{W}$  to construct the GMM estimator.